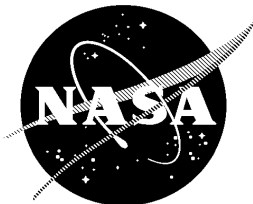


Earth Orbiter-1 (EO-1) Spacecraft to Wideband Advanced Recorder/Processor (WARP) Interface Control Document



National Aeronautics and
Space Administration

Goddard Space Flight Center
Greenbelt, Maryland

**Earth Orbiter-1 (EO-1) Spacecraft
to Wideband Advanced
Recorder/Processor (WARP)
Interface Control Document**

Goddard Space Flight Center
Greenbelt, Maryland

TBD List

| Issue | Section Number | Resolution Date | Comment |
|-------------------------------------|----------------|-----------------|---------|
| Availability of WARP I&T Procedures | 4 | | |

Change Information Page

| List of Effective Pages | | | |
|-------------------------|-----------------|----------|----------|
| Page Number | | Issue | |
| Title page | | Baseline | |
| iii | | Baseline | |
| v | | IRN 001 | |
| vii | | Baseline | |
| viii through ix | | IRN 001 | |
| 1-1 | | Baseline | |
| 2-1 | | Baseline | |
| 3-1 through 3-2 | | IRN 001 | |
| 3-3 through 3-5 | | Baseline | |
| 3-6 through 3-9 | | IRN 001 | |
| 4-1 | | IRN 001 | |
| AB-1 through AB-2 | | IRN 001 | |
| Revision | Description | Date | Approval |
| – | Initial Release | | 3/30/98 |
| IRN 001 | EO-1CCR 0018 | 9/16/98 | 11/12/98 |

Contents

Section 1. Scope

Section 2. Documents

| | | |
|-----|----------------------------|-----|
| 2.1 | Applicable Documents | 2-1 |
| 2.2 | Reference Documents | 2-1 |

Section 3. Interface Requirements

| | | |
|---------|---|-----|
| 3.1 | Interface Definition | 3-1 |
| 3.1.1 | Interface Functions | 3-2 |
| 3.2 | Mechanical Interface Requirements | 3-2 |
| 3.2.1 | Configuration | 3-2 |
| 3.2.1.1 | Coordinate System | 3-3 |
| 3.2.1.2 | Mounting Interface | 3-3 |
| 3.2.2 | Mass Properties | 3-3 |
| 3.2.2.1 | Mass | 3-3 |
| 3.2.2.2 | Center of Gravity | 3-3 |
| 3.2.2.3 | Moment of Inertia | 3-4 |
| 3.2.3 | Mechanical Design and Analysis Requirements | 3-4 |
| 3.2.3.1 | Structural Design Safety Factors | 3-4 |
| 3.2.3.2 | Loads Environment | 3-4 |
| 3.2.3.3 | Structural Stiffness Requirement | 3-4 |
| 3.2.3.4 | Stress Analysis Requirement | 3-5 |
| 3.2.3.5 | Fastener Capacity | 3-5 |

| | | |
|---------|---|------|
| 3.2.4 | WARP Handling Operations and Lift Points | 3-5 |
| 3.2.4.1 | Handling Operations | 3-5 |
| 3.2.5 | Access Requirements..... | 3-6 |
| 3.2.6 | Aperture Covers..... | 3-6 |
| 3.2.7 | Thermal..... | 3-6 |
| 3.2.7.1 | Heat Flow Across the Interface | 3-6 |
| 3.2.7.2 | Heat Input to Bay 1 Radiator | 3-6 |
| 3.2.7.3 | Design Responsibility | 3-6 |
| 3.2.7.4 | Thermal Coatings and Multilayer Insulating Blankets | 3-6 |
| 3.3 | Electrical Interface Requirements..... | 3-6 |
| 3.3.1 | Electrical Interfaces | 3-6 |
| 3.3.2 | Power Requirements | 3-7 |
| 3.3.2.1 | Power Distribution..... | 3-7 |
| 3.3.2.2 | Noise Suppression..... | 3-8 |
| 3.3.3 | WARP-to-1773 Interfaces | 3-8 |
| 3.3.4 | WARP-to-S-Band Transponder Interface | 3-8 |
| 3.3.5 | WARP-to-Instrument RS-422 Interface (Wideband Data)..... | 3-8 |
| 3.3.6 | WARP-to-X-Band Transmitter Interface | 3-8 |
| 3.3.7 | Electromagnetic Compatibility..... | 3-8 |
| 3.4 | Ordnance Requirements | 3-98 |

Section 4. Deliverables

Figures

3-1 WARP Block Diagram.....3-1

3-2 WARP Configuration.....3-2

3-3 WARP Reference Axes.....3-3

Tables

3-1 Design Safety Factors3-4

3-2 Limit Load Factor.....3-4

3-3 WARP Random Vibration Test Levels.....3-5

3-4 Connector Pinout.....3-7

3-5 Main Power Bus Specification3-8

Abbreviations and Acronyms

Section 1. Scope

This interface control document (ICD) defines all interface requirements between the Wideband Advanced Recorder/Processor (WARP) and the Earth Orbiter-1 (EO-1) spacecraft. The ICD documents all interface-related agreements concluded between the technology provider and Swales Aerospace, the spacecraft contractor.

The purpose of this document is to specify the interface requirements in order to assure compatibility between the equipment furnished by the respective contractors. Changes to this document may be proposed by either party for formal approval by the EO-1 Project Office.

This ICD will serve as the controlling technical document between the WARP and the EO-1 spacecraft. This ICD shall apply to all phases of the WARP/EO-1 design, assembly, integration, test, launch, and operations. This document is controlled by the Goddard Space Flight Center (GSFC) EO-1 Project Office.

Section 2. Documents

2.1 Applicable Documents

The following documents of the exact issue shown form a part of the ICD to the extent specified herein. In the event of conflict between this ICD and the document referenced herein, the contents of this ICD shall be considered a superseding requirement.

| | |
|-----------------|---|
| SAI-PLAN-130 | EO-1 Integration and Test Plan |
| SAI-PLAN-138 | EO-1 Contamination Control Plan |
| SAI-ICD-027 | EO-1 Spacecraft-to-Instrument FODB Terminal ICD |
| SAI-SPEC-158 | EO-1 Verification Plan and Environmental Specification |
| A0758 | WARP-to-Spacecraft Interface Control Drawing |
| | Command Handbook, Litton Amecom |
| AM149-0031(155) | EO-1 Telemetry Specification, Litton Amecom |
| AM149-0020(155) | System Level Electrical Requirements NMP EO-1 Flight, Litton Amecom |
| AM149-0050(155) | Data Systems 1773 ICD EO-1, Litton Amecom |
| AM149-XXXX(155) | EO-1 X-Band Downlink ICD, Litton Amecom |
| WARP-735-0013 | WARP S-Band ICD |
| WARP-735-0026 | EO-1 Instrument RS-422 ICD |
| | ICD for Ground Station Interface |
| | WARP to ALI ICD |
| | WARP Integration and Test Plan |

2.2 Reference Documents

| | |
|--------------|--|
| GSFC-PPL | GSFC Preferred Parts List (latest issue) |
| MIL-M-38510 | General Specification for Microcircuits |
| MIL-S-19500 | General Specification for Semiconductors |
| MIL-STD-1547 | Electronic Parts, Materials, and Processes for Space and Launch Vehicles |
| MIL-STD-975 | Standard (EEE) Parts List |
| MIL-STD-202 | Test Methods for Electronic and Electrical Components |
| MIL-STD-883 | Test Methods and Procedures for Microelectronics |

Section 3. Interface Requirements

3.1 Interface Definition

The WARP is a spacecraft component that receives, stores, and processes high-rate science data and associated ancillary data. For the EO-1 mission, these science interfaces originate at the Advanced Land Imager (ALI), ~~and the Linear Etalon Imaging Spectral Array (LEISA)~~ Atmospheric Corrector (LAC), ~~and Hyperion~~. The WARP then transmits the data to the ground via an X-band or S-band transmitter.

Figure 3-1 shows a block diagram of the WARP and its data interfaces to the spacecraft and instruments.

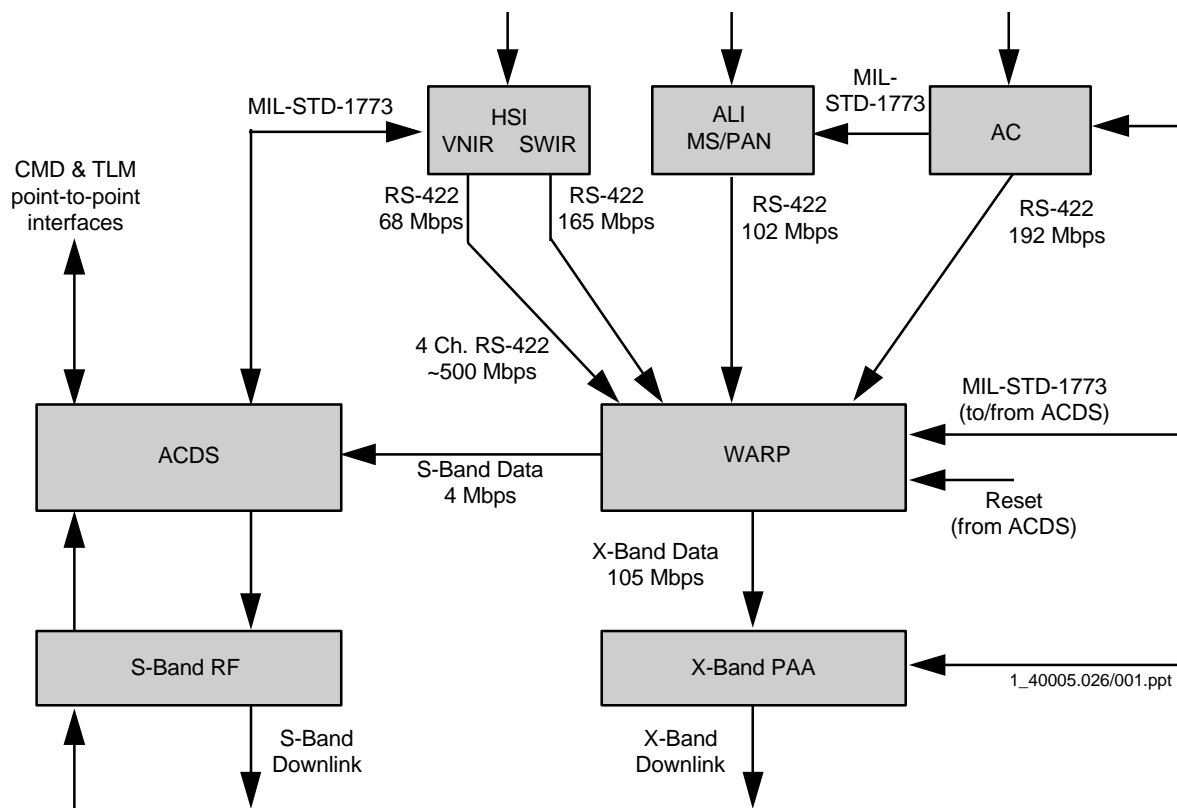


Figure 3-1. WARP Block Diagram

3.1.1 Interface Functions

The functions provided to the WARP by the spacecraft, and conversely, are delineated as follows.

- a. 1773 interface for command and telemetry.

- b. WARP transfers data to the S-band transponder via the ACDS.
- c. WARP sends high-rate science data to the X-band phased array.
- d. Spacecraft provides power at 28 ± 7 VDC.
- e. Spacecraft provides mounting interface for the WARP.
- f. Spacecraft provides thermal control during normal and survival operations.
- g. Spacecraft provides discrete command for WARP boot mode.

3.2 Mechanical Interface Requirements

The WARP is mounted on the Bay 1 equipment panel of the spacecraft. Threaded inserts shall be supplied by the spacecraft contractor, on the interior of the panel, for mounting the WARP.

3.2.1 Configuration

The dimensional drawing of the WARP on the Bay 1 equipment panel is shown in Figure 3-2. Interface Control Drawing A0758 has complete details of the mechanical interface.

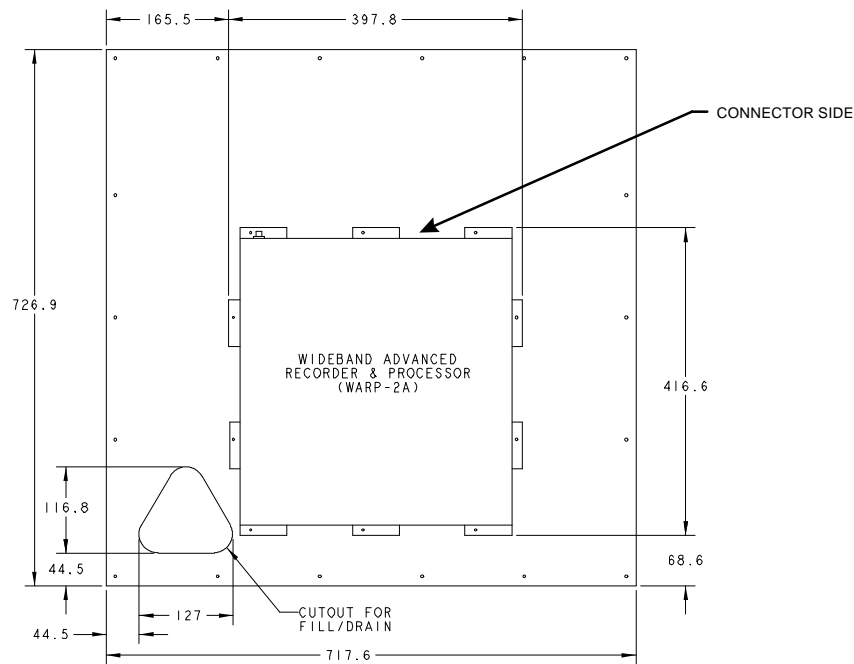


Figure 3-2. WARP Configuration

3.2.1.1 Coordinate System

Orthogonal reference axes are established for the WARP, as shown in Figure 3-3.



Figure 3-3. WARP Reference Axes

3.2.1.2 Mounting Interface

The WARP is mounted to the spacecraft at 10 attachment points, as shown in Figure 3-2.

3.2.1.2.1 Flatness Specification

The mounting points on the spacecraft shall not be out of plane more than 0.25 mm.

3.2.1.2.2 In-Plane Accuracy

The mounting point centerlines shall not change more than 0.25 mm from nominal.

3.2.2 Mass Properties

A finite element model of the EO-1 satellite will be generated to be used in the launch vehicle coupled loads analysis. To aid in this effort, the mass properties of the deliverable hardware will be required.

3.2.2.1 Mass

The total mass of the WARP shall not exceed 27 kg. All changes in mass estimates, including expected growth, shall be reported promptly. The final WARP mass shall be measured to an accuracy of 0.1 kg.

3.2.2.2 Center of Gravity

The center of gravity (CG) of the WARP shall be located, ± 12 mm, at $X_w = 195$ mm, $Y_w = 180$ mm, $Z_w = 122$ mm relative to the coordinate system, as shown in Figure 3-3. The final WARP CG shall be measured to 5 percent accuracy.

3.2.2.3 Moment of Inertia

The moment of inertia (MOI) of the instrument shall be calculated with 5 percent accuracy.

3.2.3 Mechanical Design and Analysis Requirements

3.2.3.1 Structural Design Safety Factors

All hardware shall be designed and analyzed to the applicable safety factors defined in Table 3-1. The analyses shall indicate a positive margin of safety. Limit loads are defined as the maximum expected flight loads.

Table 3-1. Design Safety Factors

| All Flight Hardware Except Pressure Vessels | Test Qual | Analysis Only |
|--|-----------|---------------|
|--|-----------|---------------|

| | | |
|---------------------------|------|-----|
| Material yield factors | 1.25 | 2.0 |
| Material ultimate factors | 1.4 | 2.6 |

3.2.3.2 Loads Environment

3.2.3.2.1 Limit Load Factor

All hardware shall be designed to withstand the quasi-static limit load (with applicable safety factors) defined in Table 3-2. This load should be applied in any direction at the component CG.

Table 3-2. Limit Load Factor

| |
|--------------------|
| $\pm 13 \text{ g}$ |
|--------------------|

3.2.3.2.2 Random Vibration

All hardware shall be designed to withstand the random vibration environment (with applicable safety factors) defined in Table 3-3.

3.2.3.3 Structural Stiffness Requirement

In the launch configuration, the WARP shall have a first mode frequency greater than 80 Hz when hard-mounted at the flight interface.

Table 3-3. WARP Random Vibration Test Levels

| Frequency (Hz) | Level | |
|----------------|--------------------------|--------------------------|
| | Acceptance | Protoflight |
| 20 | 0.013 g ² /Hz | 0.026 g ² /Hz |
| 20-50 | +6 dB/octave | +6 dB/octave |
| 50-800 | 0.08 g ² /Hz | 0.16 g ² /Hz |
| 800-2000 | -6 dB/octave | -6 dB/octave |
| 2000 | 0.013 g ² /Hz | 0.026 g ² /Hz |
| Overall | 10.0 grms | 14.1 grms |

- NOTES:**
1. Levels are for each of three orthogonal axes, one of which is normal to the mounting surface and one of which is parallel to the spacecraft z-axis.
 2. Levels are to be applied at the interface with the EO-1 spacecraft equipment panel.
 3. Test duration is 1 minute per axis.
 4. The table shows flight acceptance and protoflight test levels. These levels may be reduced in specific frequency bands, with Project concurrence, if required to preclude damage resulting from unrealistic high amplification resonant response due to the shaker mechanical impedance and/or shaker/fixture resonance.
 5. Flight-type attach hardware (including any thermal washers, etc.) shall be used to attach the component to the test fixture, and preloads and fastener locking features shall be similar to the flight installation.
 6. Cross-axis responses of the fixture shall be monitored during the test to preclude unrealistic levels.

3.2.3.4 Stress Analysis Requirement

A stress analysis shall be performed to verify the integrity of the component structure and attachments when subjected to the specified loads with the applicable safety factors. Margins of safety shall be determined, dominant failure modes identified, and this information transmitted to the satellite integrator. Existing mechanical stress analysis reports and data may be used if applicable.

3.2.3.5 Fastener Capacity

The deliverable hardware will be attached to the spacecraft panel using threaded fasteners. A positive margin factor of safety shall be maintained for all the fasteners used on the spacecraft. The maximum load on any fastener shall not exceed 667 N (150 lb) axial and 1223 N (275 lb) shear.

3.2.4 WARP Handling Operations and Lift Points

3.2.4.1 Handling Operations

Normal care shall be exercised during handling and installation of the equipment. Protective covers shall be supplied by the WARP contractor for protection of the hardware.

3.2.5 Access Requirements

Access requirements to the WARP shall be as defined in WARP Integration and Test (I&T) Plan. Access requirements include connector mate/demate clearances, removal and replacement clearances for electronic components and protective covers, and access to purge fittings.

3.2.6 Aperture Covers

There will be no red-flag cover or other items on the WARP.

3.2.7 Thermal

The WARP electronic box shall be thermally coupled to the Bay 1 spacecraft equipment panel.

3.2.7.1 Heat Flow Across the Interface

The maximum allowable heat flow from all sources and interface temperatures during normal operations and survival operations is 0.4 W/in^2 . The WARP base plate at the spacecraft interface shall have an irridite coating with ChoTherm as an interface material between the WARP base plate and the spacecraft.

3.2.7.2 Heat Input to Bay 1 Radiator

The environmental heat flux on the Bay 1 radiator shall be between 0 and 70 W. The radiator optical properties are for Silver Teflon and 3 mil Kapton. The radiators are sized assuming hot environment and end-of-life degraded thermal coating properties.

3.2.7.3 Design Responsibility

The spacecraft contractor is responsible for the thermal analysis of the combined WARP and spacecraft. The technology provider will supply a thermal design, analysis, and model to the spacecraft contractor.

3.2.7.4 Thermal Coatings and Multilayer Insulating Blankets

GSFC is responsible for all external optical coatings for the WARP. The spacecraft contractor is responsible for all externally located multilayer insulating (MLI) blankets.

3.3 Electrical Interface Requirements

3.3.1 Electrical Interfaces

There are four electrical interfaces to the WARP:

- RS-422 from ALI, AC, and Hyperion~~the Fiber Optic Data Bus (FODB)~~
- Power from PSE
- RS-422 to ACDS

- Terminal control for the Fiber Optic Data Bus (FODB) terminal box
- Modulated X-band to X-band Phased Array Antenna (PAA)

In addition, there ~~is one~~~~are two~~ optical data bus~~es~~: 1773~~_, and the high-rate FODB~~

3.3.2 Power Requirements

The spacecraft operating bus voltage and power characteristics are as specified in System Level Electrical Requirements NMP EO-1 Flight, Litton Amecom document AM-149-0020(155) and Avionics Requirements Specification. GSFC shall ensure that the WARP shall successfully operate within this power regime.

3.3.2.1 Power Distribution

The WARP will require a single connector for +28 V power input to and return from the WARP LVPC. The WARP will draw 4.6 A at peak and 1.5 A for orbital average. The +28 V power input ~~from the spacecraft~~ shall use a DB-15~~p9~~ connector on the WARP. The wires into the WARP LVPC power input connector shall be 20 AWG. The connector pinout is shown in Table 3-4.

Table 3-4. Connector Pinout

| Pin Number | Connection |
|------------|---------------------|
| 1 | +28 V |
| 2 | +28 V |
| 3 | +28 V |
| 4 | +28 V |
| 5 | <u>+28 V</u> |
| 6 | <u>+28 V</u> |
| 7 | <u>+28 V</u> |
| 8 | <u>NC</u> |
| 9 | <u>+28 V Return</u> |
| <u>10</u> | <u>+28 V Return</u> |
| <u>11</u> | <u>+28 V Return</u> |
| <u>12</u> | <u>+28 V Return</u> |
| <u>13</u> | <u>+28 V Return</u> |
| <u>14</u> | <u>+28 V Return</u> |
| <u>15</u> | <u>+28 V Return</u> |

The WARP LVPC shall be designed in accordance with the specification for the spacecraft main power bus as shown in Table 3-5 and described in the System Level Electrical Requirements NMP EO-1 Flight, Litton Amecom document AM-149-0020(155).

Table 3-5. Main Power Bus Specification

| Electrical Specification | Value |
|--------------------------|---------------------------------|
| Voltage regulation | 28 ± 7 V |
| Transients | ≤ 5 V |
| Ripple and spikes | ≤ 1.5 V p-p (DC to 10 MHz) |
| Inrush current | < 56 A for 1 ms |
| Harness output impedance | per Litton Specification |

WARP power consumption is as shown in Table 3-6. Note that these values include the power consumption of the IFT, as its power is provided by the WARP.

Table 3-6. WARP Power Consumption

3.3.2.2 Noise Suppression

All inductive loads associated with the WARP, such as relay coil circuits, shall be provided with suppression circuits to prevent excessive transients and associated EMC noise due to power interrupts. For further details, refer to the System Level Electrical Requirements NMP EO-1 Flight, Litton Amecom document AM-149-0020(155).

3.3.3 WARP-to-1773 Interfaces

The WARP receives and transmits control and status to the spacecraft via a MIL-STD-1773 serial fiber optic bus. For further details, refer to the Data Systems 1773 ICD EO-1, Litton Amecom document AM-149-0050(155).

3.3.4 WARP-to-S-Band Transponder Interface

The WARP transmits S-band telemetry downlink data to the spacecraft Command and Data Handling (C&DH) system via a serial RS-422 interface. The S-band interface will support the 24-Mbps rate requirement. For further details, refer to the WARP S-Band ICD (WARP-735-0013).

3.3.5 WARP-to-Instrument RS-422 Interface (Wideband Data)

Science data are transmitted from the instruments to the WARP across a parallel RS-422 interface. This interface will have a throughput capability of 840 Mbps under all operational conditions. For further details, refer to the EO-1 Instrument RS-422 ICD (WARP-735-0026).

3.3.6 WARP-to-X-Band Transmitter Interface

The WARP will provide an X-band modulated output at a rate of 105 Mbps. The WARP will provide fill data for sync acquisition and for unequal length I and Q data streams. For further details, refer to the EO-1 X-Band Downlink ICD, Litton Amecom document AM-149-XXXX(155).

3.3.7 Electromagnetic Compatibility

For further details, refer to the System Level Electrical Requirements NMP EO-1 Flight, Litton Amecom document AM-149-0020(155).

3.4 Ordnance Requirements

There are no electro-explosive devices used on the WARP.

Section 4. Deliverables

| Item | Delivered By | Delivered To | Need Date | Comment |
|---------------------|--------------|--------------|-----------|---------|
| WARP box | GSFC | Swales | 6/24/98 | |
| WARP software | GSFC | Swales | 6/24/98 | |
| WARP EGSE | GSFC | Swales | 6/24/98 | |
| WARP I&T Procedures | GSFC | Swales | TBD | |

NOTE: Harness delivered at same time as flight.

Abbreviations and Acronyms

| | |
|-----------------|---------------------------------------|
| A | ampere |
| <u>AC</u> | <u>Atmospheric Corrector</u> |
| ACDS | |
| ALI | Advanced Land Imager |
| AWG | |
| bps | bits per second |
| CG | center of gravity |
| C&DH | Command and Data Handling |
| <u>DC</u> | <u>direct current</u> |
| dB/octave | decibel per octave |
| EGSE | ?electrical ground support equipment? |
| EO-1 | Earth Orbiter-1 |
| FODB | Fiber Optic Data Bus |
| g | gram |
| g^2/Hz | |
| grms | |
| GSFC | Goddard Space Flight Center |
| <u>HSI</u> | |
| Hz | hertz |
| I&T | Integration and Test |
| ICD | interface control document |
| IFT | |
| kg | kilogram |
| LAC | LEISA Atmospheric Corrector |
| lb | pound |
| LEISA | Linear Etalon Imaging Spectral Array |
| LVPC | |
| Mbps | megabits per second |

| | |
|-------------------|--------------------------------------|
| MHz | megahertz |
| MLI | multilayer insulating |
| mm | millimeter |
| MOI | moment of inertia |
| ms | millisecond |
| <u>MS</u> | <u>multispectral</u> |
| NMP | New Millennium Program |
| <u>PAA</u> | <u>Phased- Array Antenna</u> |
| <u>PAN</u> | <u>panchromatic</u> |
| PSE | |
| <u>SWIR</u> | <u>shortwave infrared</u> |
| TBR | to be resolved |
| V | volt |
| VDC | <u>volt direct current</u> |
| <u>VNIR</u> | <u>visible and near infrared</u> |
| W | watt |
| W/in ² | watts per square inch |
| WARP | Wideband Advanced Recorder/Processor |